

Knowing When to Parallelize

Rules-of-Thumb based on User Experiences

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What is Parallelism?

- Consider your favorite computational application
 - One processor can give me results in N hours
 - Why not use N processors
 - and get the results in just one hour?

The concept is simple:

Parallelism = applying multiple processors to a single problem

- Reasons for using parallelism
 - Get results faster
 - Solve bigger problems
 - Run simulations at finer resolutions
 - Model physical phenomena more realistically




Parallelism Carries a Price Tag

- Parallel programming
 - Involves a steep learning curve
 - Is effort-intensive
- Parallel computing environments are unstable and unpredictable
 - Don't respond to many serial debugging and tuning techniques
 - May not yield the results you want, even if you invest a lot of time

Will the investment of your time be worth it?

- Rules-of-thumb
 - Drawn from the experiences of hundreds of computational scientists and engineers
 - Encapsulate their “tricks” for knowing when to parallelize (and when to keep their applications serial)

Test the “Preconditions for Parallelism”

		Frequency of Use	Execution Time	Resolution Needs
positive pre-condition		thousands of times between changes Δ	days Δ	must significantly increase resolution or complexity Δ
possible pre-condition		dozens of times between changes Δ	4-8 hours Δ	want to increase to some extent Δ
negative pre-condition		only a few times between changes Δ	minutes Δ	current resolution/complexity already more than needed Δ

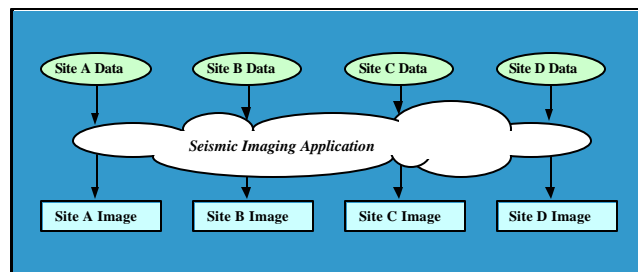
- According to experienced parallel programmers:
 - **no green** - Don't even consider it
 - **one or more red** - Parallelism may cost you more than you gain
 - **all green** - You need the power of parallelism (but there are no guarantees)

How Your Problem Affects Parallelism

- The nature of your problem constrains how successful parallelization can be
- Consider your problem in terms of
 - When data is used, and how
 - How much computation is involved, and when
- Geoffrey Fox identified the importance of problem architectures
 - Perfectly parallel
 - Fully synchronous
 - Loosely synchronous
- A fourth problem style is also common in scientific problems
 - Pipeline parallelism

Perfect Parallelism

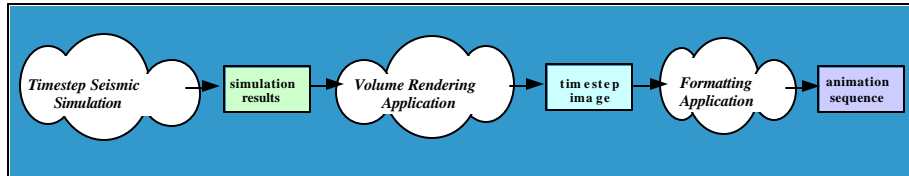
- Scenario: seismic imaging problem
 - Same application is run on data from many distinct physical sites
 - Concurrency comes from having multiple datasets processed at once
 - Could be done on independent machines (if data can be available)



- This is the simplest style of problem
- Key characteristic: calculations for each data set are independent
 - Could divide/replicate data into files and run as independent serial jobs (also called “job-level parallelism”)

Pipeline Parallelism

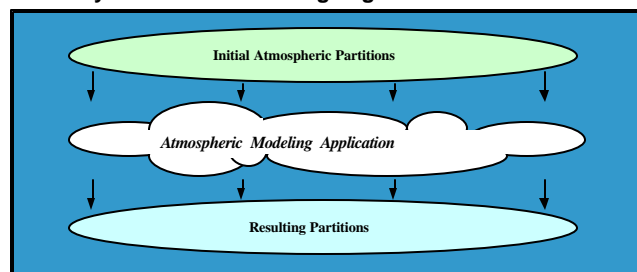
- Scenario: seismic imaging problem
 - Data from different time steps used to generate series of images
 - Job can be subdivided into phases which process the output of earlier phases
 - Concurrency comes from overlapping the processing for multiple phases



- Key characteristic: only need to pass results one-way
 - Can delay start-up of later phases so input will be ready
- Potential problems
 - Assumes phases are computationally balanced
 - (or that processors have unequal capabilities)

Fully Synchronous Parallelism

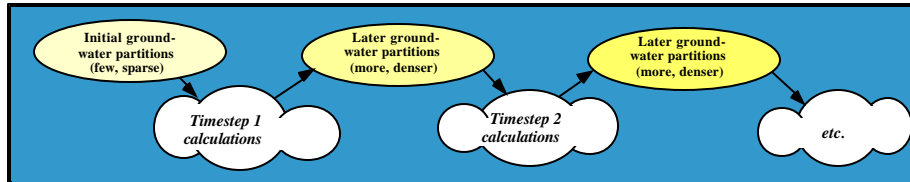
- Scenario: atmospheric dynamics problem
 - Data models atmospheric layer; highly interdependent in horizontal layers
 - Same operation is applied in parallel to multiple data
 - Concurrency comes from handling large amounts of data at once



- Key characteristic: Each operation is performed on all (or most) data
 - Operations/decisions depend on results of previous operations
- Potential problems
 - Serial bottlenecks force other processors to “wait”

Loosely Synchronous Parallelism

- **Scenario: diffusion of contaminants through groundwater**
 - ↳ Computation is proportional to amount of contamination and geostructure
 - ↳ Amount of computation varies dramatically in time and space
 - ↳ Concurrency from letting different processors proceed at their own rates

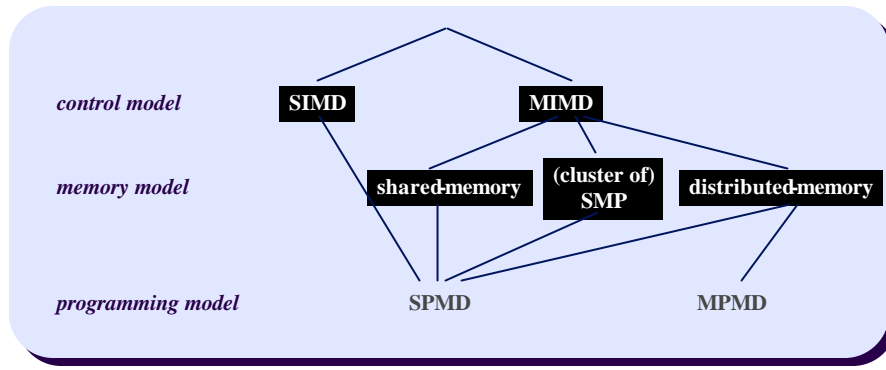


- **Key characteristic: Processors each do small pieces of the problem, sharing information only intermittently**
- **Potential problems**
 - ↳ Sharing information requires “synchronization” of processors (where one processor will have to wait for another)

Rules-of-Thumb Based on Type of Problem

- If your application fits the model of perfect parallelism
 - the parallelization task is relatively straightforward and likely to achieve respectable performance
- If your application is an example of pipeline parallelism
 - you have to do more work. If you can't balance the computational intensity, it may not prove worthwhile
- If your application is fully synchronous
 - a significant amount of effort is required and payoff may be minimal. The decision to parallelize should be based on how uniform computational intensity is likely to be
- A loosely synchronous application is the most difficult to parallelize
 - it's probably not worthwhile unless the points of CPU interaction are very infrequent

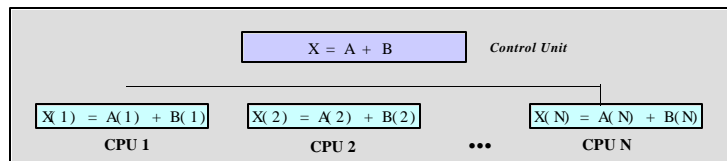
How the Machine Affects Parallelism



"Genealogy" of parallel computing systems

SIMD Computer (Processor Array)

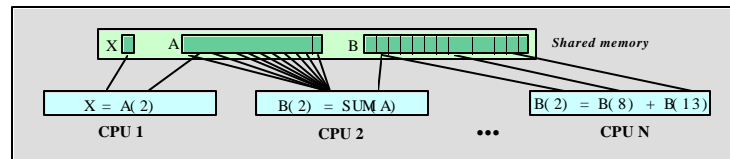
- All processors execute the same instruction in "lockstep"
 - Examples: Maspar, Thinking Machines (CM-2)



- Major programming hurdle:
 - Must use Fortran-90 style array operations efficiently
- Highlights:
 - Efficient use of memory
 - Relatively easy to program
- Lowlights:
 - Programming is difficult or impossible if application isn't fully synchronous
 - All processors perform every operation (even scalar addition or conditional op)

Shared-Memory MIMD Computer

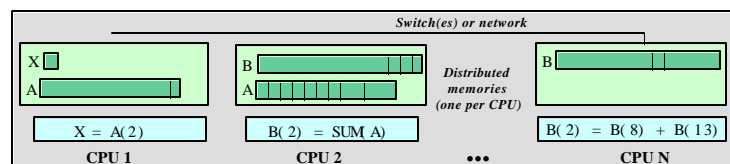
- Each processor executes its own instruction
 - Processors interact by accessing shared memory locations
 - Examples: Cray Y/MP and C-90/J-90, Fujitsu, IBM ES/9000



- Major programming hurdle:
 - Must use compiler directives to protect access to shared data locations
- Highlights:
 - Blindingly fast
 - Large memory
- Lowlights:
 - Very expensive
 - Can be hard or impossible to restructure computational loops effectively

Distributed-Memory MIMD Computer

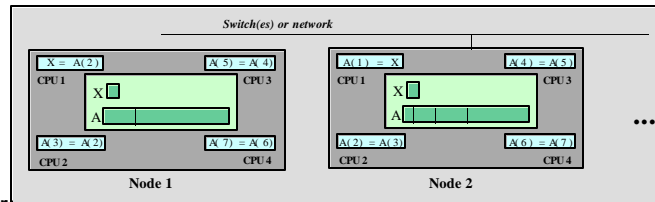
- Each processor executes its own instruction
 - Processors interact via a communication system
 - Examples: IBM SP2, Intel, Meiko, SGI/Cray T3 series



- Major programming hurdle:
 - Must use message-passing (or equivalent) and minimize communications
- Highlights:
 - Versatile
 - Cost-effective
- Lowlights:
 - Hard to use efficiently
 - Can be very hard to debug race conditions and deadlocks

SMP (Symmetric Multiprocessor) Clusters

- Cross between shared- and distributed- memory systems
 - Small group of processors share a common memory (SMP “node”)
 - Clustered into larger configurations using a communication system
 - Examples: SGI PowerChallenge & Origin, HP/Convex Exemplar, Sun SPARCServer

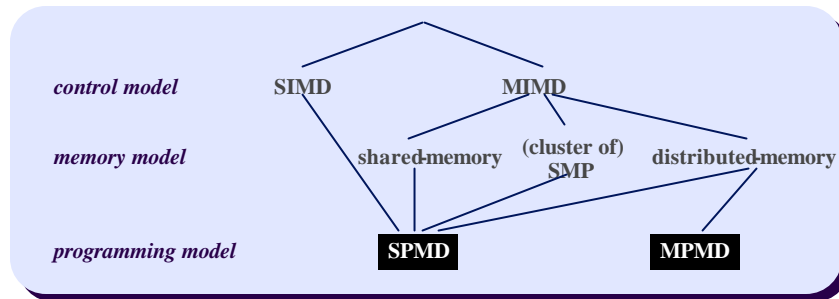


- Major programming nature.
 - (Within a node) must protect access to shared data
 - (Off-node) must minimize amount of communication
- Highlights:
 - Versatile
 - Cost-effective
- Lowlights:
 - Hard to use efficiently
 - Problems with race conditions, deadlock

Rules-of-Thumb Based on Type of Machine

- If your application is perfectly parallel
 - it will probably perform reasonably well on any MIMD architecture, but may be difficult to adapt to a SIMD computer
- If your application is pipeline parallelism
 - it will probably perform best on a shared-memory machine or clustered SMP (where a given stage fits on a single SMP)
 - it should be adaptable to a distributed-memory computer as well, as long as the communication network is fast enough to pipe the data sets from one stage to another
- If your application is fully synchronous
 - it will perform best on a SIMD computer, if you can exploit array operations
 - it may be respectable on a shared-memory computer (or clustered SMP, if a small number of CPUs is sufficient), but only if the computations are fairly independent
- If your application is loosely synchronous
 - it will perform best on a shared-memory computer (or clustered SMP, if a small number of CPUs is sufficient)
 - it may be respectable on a distributed-memory computer, but only if there are many computations between CPU interactions

How Programming Language Affects Parallelism



SPMD model

- u (Functionally equivalent to MPMD)
- u Each processor executes same object code
- u Data storage areas and instructions must be resident on all CPUs
- u “Natural” model for SIMD machines
- u Convenient for MIMD compiler/tool writers

MPMD model

- u Each processor can execute different object code
- u Each CPU has only the data/instructions it will need to access
- u “Natural” model for MIMD machines (but supported on only a few)
- u Convenient for MIMD users

Varieties of Programming Languages

Control-parallel: computational work subdivided across CPUs, which periodically synchronize their activities

- u Examples: VP Fortran, Cray Autotasking, *ANSI X3H5 Fortran*, *OpenMP*
- u Model: SPMD on shared-memory computers

Data-parallel: data domain subdivided across CPUs, which provide copies of data they “own” to other CPUs

- u Examples: CM-Fortran, C*, MasPar’s MPF, *HPF*, *Data Parallel C*
- u Model: SIMD (first three), SPMD on distributed-memory computers (last two)

Message-passing: Each CPU executes independently; messages are sent when they need to share data or synchronize activities

- u Examples: *PVM*, *MPI*, Intel’s NX, p4, Express, Fortran M
- u Model: MPMD on distributed-memory computers (first five), SPMD (Fortran M)

Combined: Hybrid of 2 or more (e.g., control-parallel subroutines that send messages to each other)

- u Examples: pC++, Convex Fortran, Convex C
- u Model: MPMD on distributed-memory computers (pC++), SPMD (last two)

(Italicized examples are *standards*, intended to be supported across multiple vendors)

Rules-of-Thumb Based on Type of Language

Pie-in-the-sky viewpoint:

Any problem can be programmed in any language,
for execution on any parallel computer

Realistic viewpoint:

No current machine offers much choice among compilers
Programmers are usually comfortable with 1 or 2 languages
Libraries or associated applications don't interface with just
any language

- With few exceptions, you don't really choose a parallel language
→ it chooses you

Setting Realistic Expectations

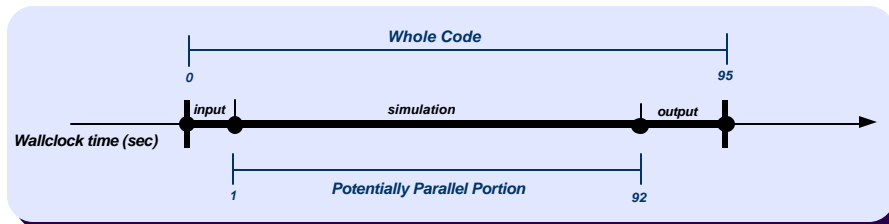
Nobody wants parallelism ... what we want is performance

– Ken Neves (Boeing)

- Suppose a serial application has been parallelized to run on 50 CPUs
 - It's using computing resources
 - If results aren't ready much, much faster, resources are being wasted
 - It took somebody a lot of time to parallelize it
 - If performance isn't reasonable, it's a waste of human productivity, too
- How can you estimate whether your efforts will be wasted?
 - Assess your application's potential before committing to parallelism
- Should a parallel program be built from scratch?
 - Computer scientists say "yes"
 - Only 1/3 of parallel programmers report doing so (primarily computer scientists or mathematicians)
- An existing, well-written serial application can facilitate the parallelization process
 - Baseline for checking the validity of parallel program results
 - Baseline for measuring performance improvements
 - ... and some (or most) of the code can be cut-and-pasted into the parallel program

Time the Performance of Your Baseline

- Use your baseline program to estimate its potential parallel performance
(If it's implemented sloppily, clean it up first!)
- Insert calls to timing routines as the program's first and last statements, to acquire whole-code time
- Insert calls to timing routines just before and after each section with potential for parallelism
 - ↳ Collectively, these represent the potentially-parallel code
 - ↳ Exclude all potential serial bottlenecks
 - ↳ Input or output phases
 - ↳ Inherently serial operations (e.g., global summations)



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Estimate the Effects of Parallelism

- Goal: reduce the whole-code time so results are produced faster
- Calculate the program's parallel content

$$p = \frac{\text{potentially parallel time}}{\text{whole code time}} = \frac{90}{93} = 0.9677$$

Parallel content indicates what proportion of code can be parallelized

- ↳ 96.77% of the code is potentially parallelizable
- ↳ 3.2% must run serially
- Apply Amdahl's law to calculate theoretical speedup

$$\text{theoretical speedup} = \frac{1}{(1-p) + (p/N)} = \frac{1}{0.323 + (0.9677/N)}$$

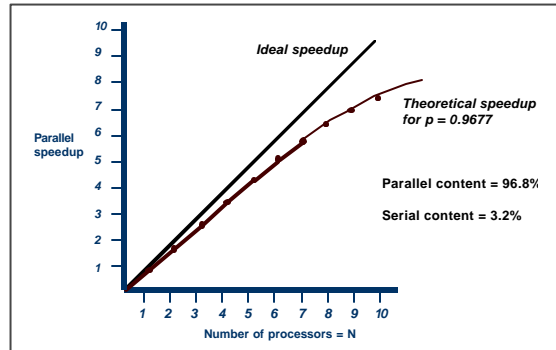
as a function of the number (N) of CPUs that will be used
- Ideally, applying N CPUs to a program should cause it to run N times faster
- Theoretical speedup shows the effects of even a small proportion of serial content

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Estimate the Effects of Parallelism (cont.)

- **Gap between ideal and theoretical speedup widens as N increases**
 - Gap is solely a function of the program's serial content
 - For every program and problem size, it is not worthwhile to go beyond some value of N

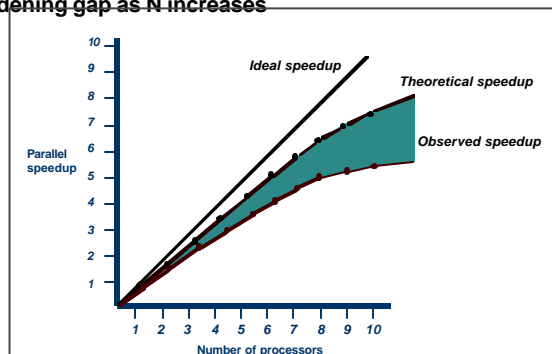


Number of CPUs	Theoretical Speedup
1	1.000
2	1.937
3	2.818
4	3.647
5	4.428
6	5.167
7	5.863
8	6.525
9	7.152
10	7.752
...	...
∞	30.959

- Suppose we greatly increase the size of the problem to be solved
 - How does this affect potential parallel content?
 - Does it change the theoretical speedup curve?

Theory versus Reality in Parallel Execution

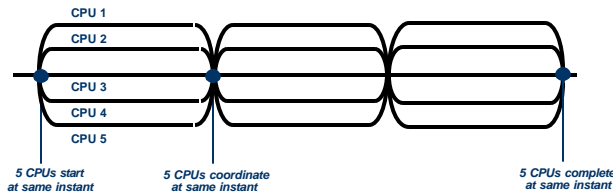
- **Observed speedup** is even less than theoretical speedup
 - Again, a widening gap as N increases



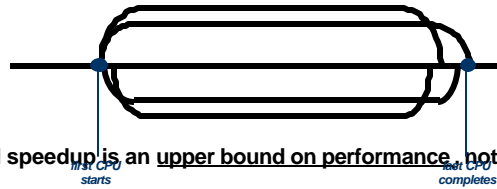
- Theoretical curve (based on Amdahl's Law) does not take into account the **overhead** of parallelism
 - CPU cycles spent managing parallelism
 - delays or wasted time (waiting for I/O or communications, competition from OS)

Theory versus Reality (cont.)

- Theoretical speedup assumes perfect concurrency
 - All CPUs begin, interact, and complete at the same time



- Real applications are subject to subtle variations in timing



- Theoretical speedup is an upper bound on performance, not a realistic estimate

Estimate the Effects of Program Granularity

- Concurrency worsens as the number of CPU interactions increases
- Granularity: rough measure of how many computations occur between CPU interactions
 - Coarse-grained programs execute many computations between interactions
 - Fine-grained programs interact frequently, with relatively few intervening computations
- For shared-memory computers, it's hard to estimate how coarse-grained the program must be to perform well
- For distributed-memory computers and SMP clusters, it's possible to calculate the message-equivalent
 - Based on machine properties that are generally available
 - Provides an indication of how many computations need to occur between CPU interactions

Estimate the Effects of Program Granularity (cont.)

Latency: Time (in microseconds) required to initiate the transmission of data

Bandwidth: Speed (in megabytes/second) at which data are transmitted

- Together, they indicate the cost of CPU interactions
 - Latency is “fixed overhead” (same cost, regardless of amount of data sent)
 - Bandwidth is “variable overhead” (cost is a function of how much data is sent)
- Nominal cost of sending a message (or other CPU interactions)

$$\text{message time} = \text{latency} + \frac{\text{message size}}{\text{bandwidth}}$$

- Real cost is the amount of time “lost” as your application waits for a CPU interaction to complete

Estimate the Effects of Program Granularity (cont.)

- Message-equivalent indicates how many floating-point operations could be done in the time needed to send one 1,024-byte message

$$\text{message equivalent} = \text{CPU speed} * [\text{latency} + (1K / \text{bandwidth})]$$

CPU speed is the so-called “peak speed” of a single CPU (in MFLOPS)

	Peak CPU (MFLOPS)	Latency (microsec)	Bandwidth (MB/sec)	Message- equivalent
System A	100	2000	1	300,000
System B	200	300	8	85,000
System C	100	20	50	4,000
System D	150	5	30	5,700
System E	150	25	10	18,750

- Good performance requires that computation exceed the message-equivalent on a regular basis
 - Very coarse-grained programs will succeed anywhere
 - None of the example systems would tolerate a medium- or fine-grained program

Rules-of-Thumb Based on Assessment

- If you have a “clean” serial application
 - timing it will provide you with a solid starting point for estimating potential payoffs
- If the parallel content of your application is less than 95%, you probably shouldn't consider parallelizing it
 - unless you're already experienced in parallel programming, or
 - unless you'll be able to dramatically reduce the serial content by substituting a parallel algorithm that has been proven to perform well
- Apply your knowledge of the application to estimate how theoretical speedup will change as problem size grows
 - you will certainly observe less speedup than that (since theoretical speedup is an upper bound on what is possible)
- If your application is coarse-grained
 - it will perform relatively well on any parallel computer
- If your application is fine-grained
 - it will probably won't perform unless you can run it on a SIMD computer
- If you will be using a distributed-memory computer or SMP cluster
 - calculate the message-equivalent to see how many thousands of FLOPs your application needs to perform between each CPU interaction point

Parallel Performance - Fact or Fantasy?

- How much performance can we get?
- Bicycle analogy:
 - I can't ride my bicycle faster than 30 MPH (peak)
 - Speed on an average ride depends on environmental conditions
 - I typically achieve 10 MPH (sustained)
- Parallel computing equivalent:
 - Vendor X claims that the HypoMetaStellar is a 200 GFLOPS machine
 - Shows benchmark results that the HypoMetaStellar is worth 10 Crays
 - What counts is the fraction of peak performance that can be sustained

For real applications, that value is probably only 10% - 20%

Is Parallelism for You?

- Actual performance will depend on 5 critical factors
 - (1) inherent parallelism in the application
 - (2) multiprocessor architecture
 - (3) how well the compiler or parallel library exploits the architecture
 - (4) how the program maps the problem to the machine
 - (5) scheduling policies on the machine
- An application's parallel content constrains even its theoretical performance
 - If there's more than a tiny fraction of serial content, parallelism almost certainly won't pay off
 - Changing the problem or the algorithm to reduce serial content will have more impact than whatever effort you can put into tuning
- The parallel machine and the runtime environment are probably out of your control
- The efficiency of the language and runtime system are beyond *any* programmer's control
- That leaves the efficiency of your program in mapping your problem to the parallel computer ...

How much effort are you willing to invest?

Is Parallelism for You? (cont.)

- Consider what you hope to gain and how much it will buy you in time or quality
- Consider the propensity your application seems to have for parallelism
- Estimate the best performance you could possibly get through parallelization
- Factor in how well you think your own efforts need to pay off
- (Assuming there are no counter-indications, such as a mismatch between your problem architecture and the type of machine available to you) Make sure the upper-bound estimate on future performance is at least 5-10 times bigger your "bottom-line price"
- *Theoretically*, any problem can be programmed in any language for execution on any parallel computer
- *Realistically* ...

If a problem doesn't lend itself to parallelism,
or if it doesn't match your computer's capabilities,
parallelization simply won't be worth the effort